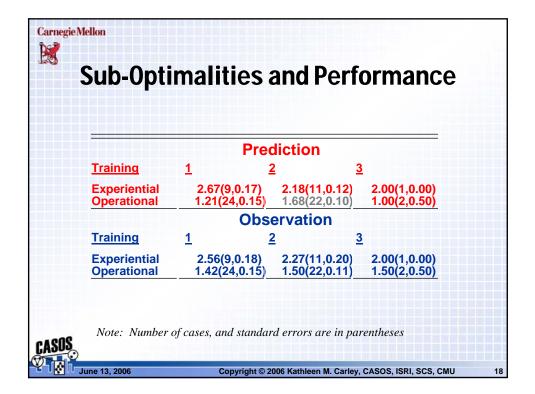
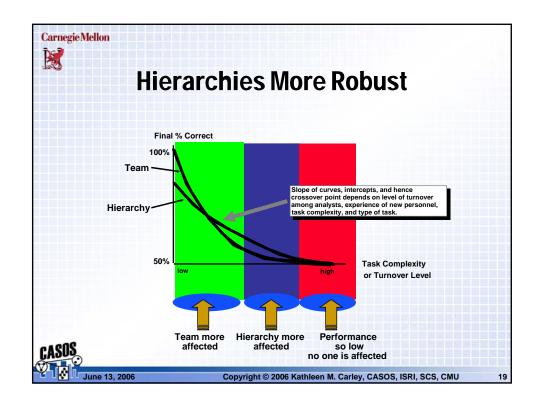
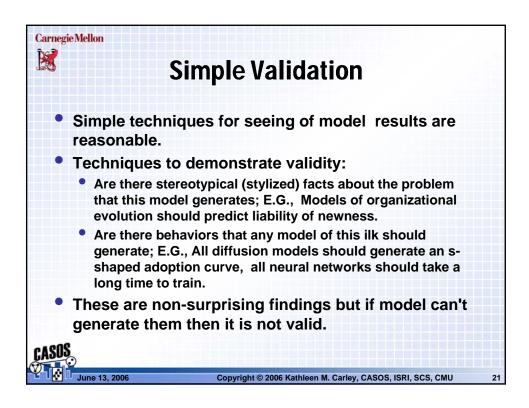


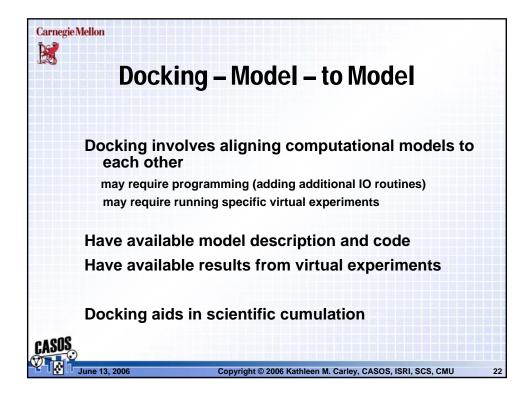
	Archival Match	
	Prediction	
Training	Performance in	Performance
	General	During Crisis
Experiential	2.10(21,0.18)	2.38(21,0.11
Operational	1.83(48,0.10)	1.42(48,0.07
	Observation	
Training	Performance in	Performance
	General	During Crisis
Experiential	1.86(21,0.17)	2.38(21,0.13
Operational	1.83(48,0.09)	1.46(48,0.08

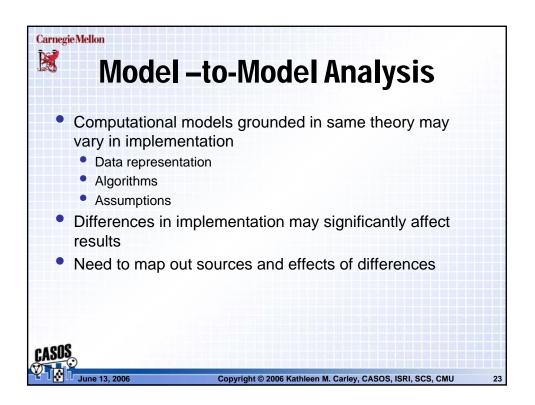


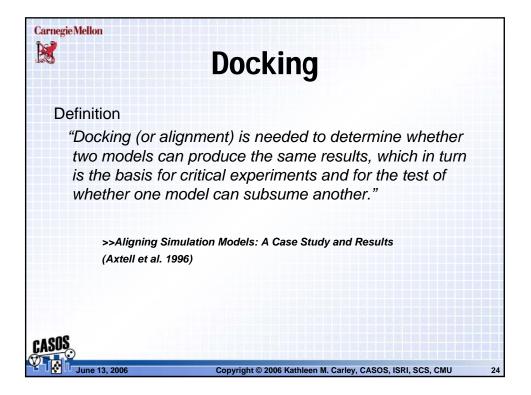


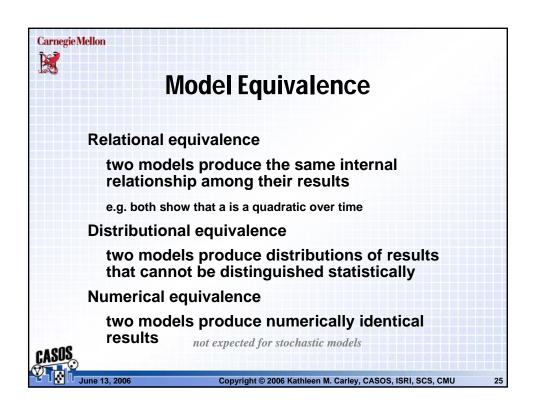
	Re	ealit	t y: 1	[ean	ns B	ette	r			
		TE/ exp	\M sop	HIERAI exp			REG sop		-SEG sop	
:	Simulated	3.00	1.50	2.35	1.41	2.30	1.40	2.45	1.60	
	Human	3.00 (1)	1.50 (4)	2.35 (20)			1.42 (43)	2.64 (11)	1.80 (5)	

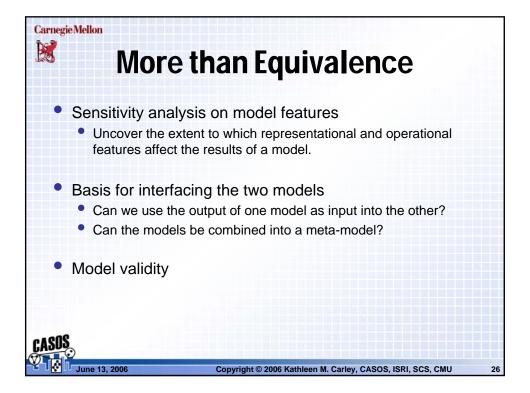


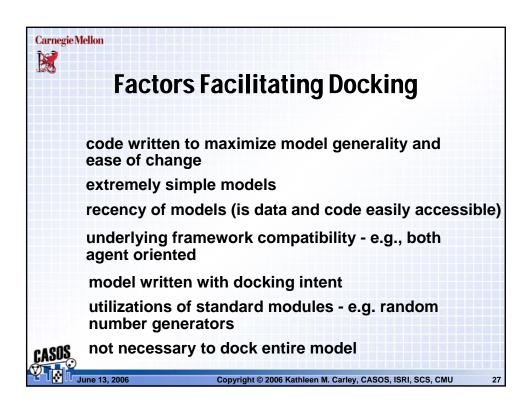


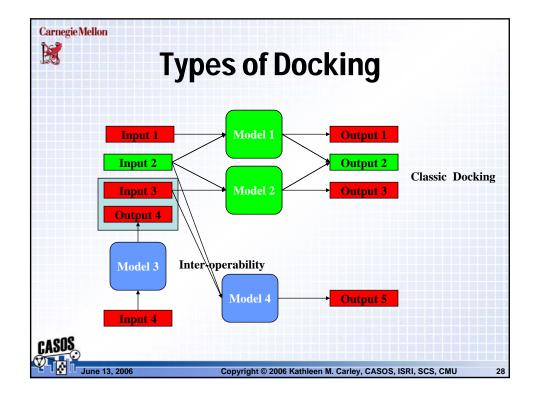


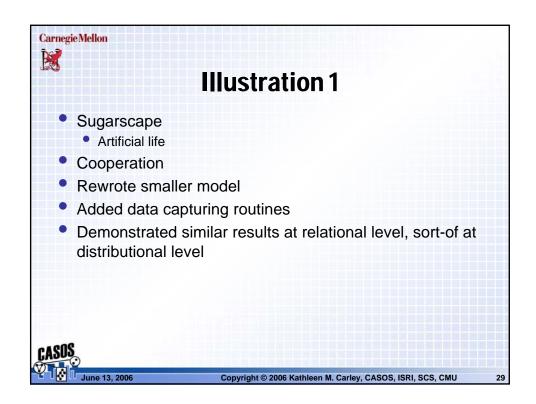


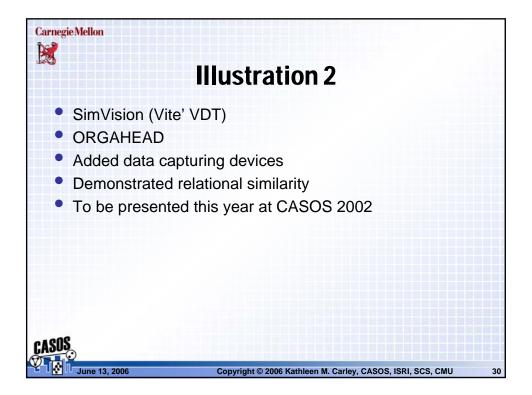


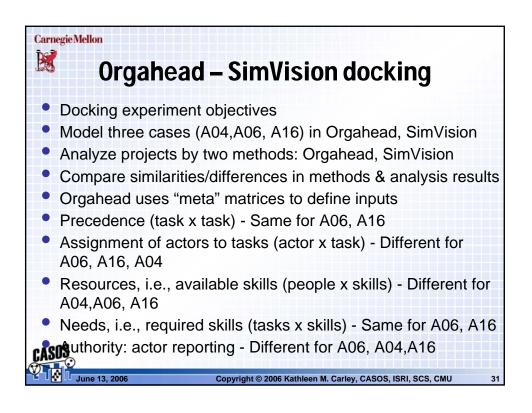


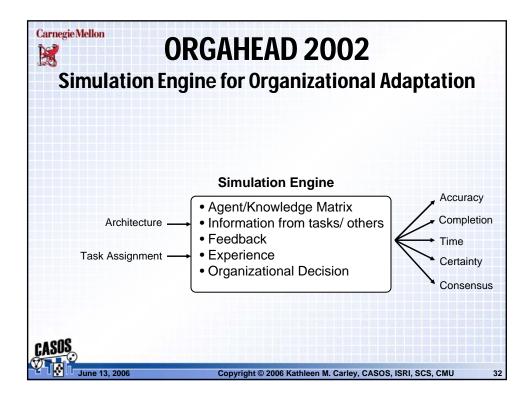


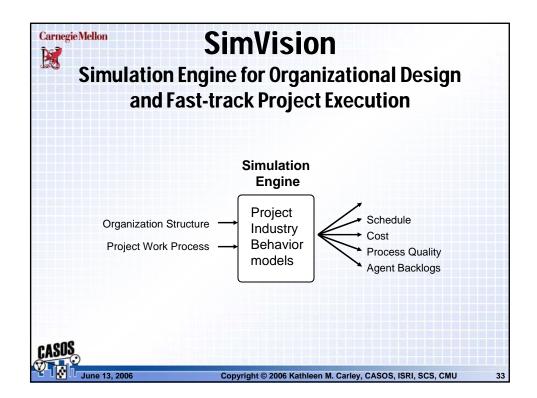








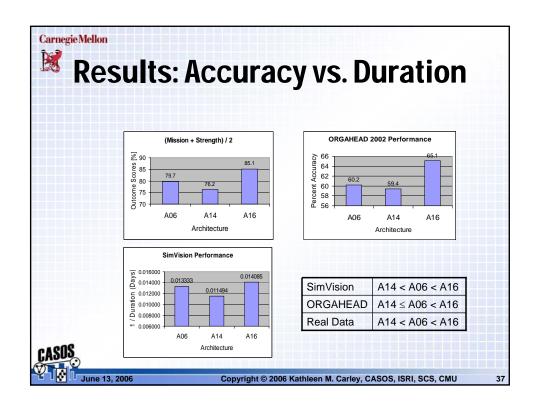


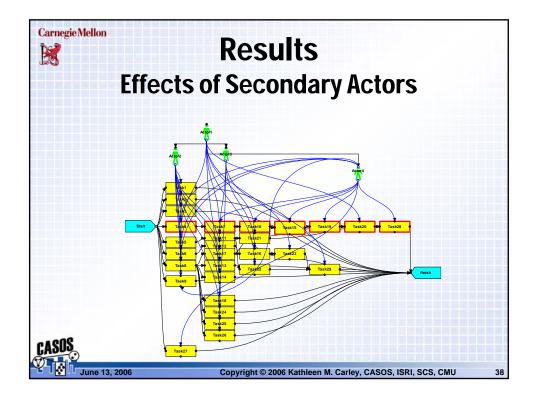


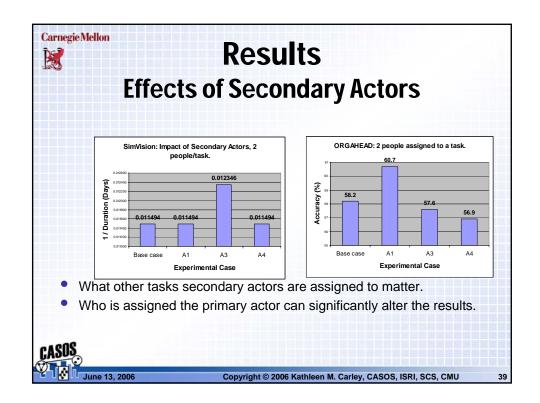
Orgahea	d _ SimVis	sion features
organica		Sion reator c3
	Orgahead	SimVision
Tasks	√	✓
Task duration		✓ Soon
Task required skills	[1-n]	[1]
		Assume first required
Task precedence		\checkmark
Actor responsibility	[0-n]	[1]
		Assume first specified is
		primary; others secondary
Actor provides feedback	v	
Task rework		 (N/A for this experiment)
Coordination	Actor - actor	Task – Task
		(Not included in 7.11 analysis

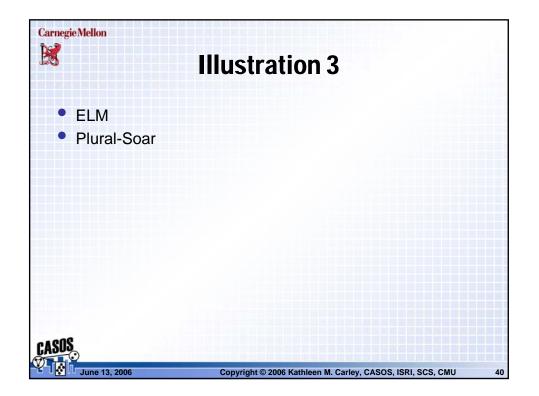
2	Encoding	g the Da	ta
		ORGAHEAD 2002	SimVision
	Authority Structure	Yes	Yes
	Resource Requirements	1 to many	Assume 1 st required
	Resource Assignment	1 to many	Assume 1 st required
	Tasks	Binary bit string	Symbolic
	Task Precedence	Simulated	Yes
	Task Assignment	1 to many	Assume 1 st specified

Carnegie Mellon	ead — SimVision Task – actor assignments
Case	e A06
Acto Yellow	ers (rows) by tasks (columns) v cells show tasks assigned by default to the actor with the best skill match.
Blue o	cells show tasks and their assigned secondary actors
Task a	actor assignments A06 (actor x task)
	1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9
	1 1 0 1 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	2 0 1 0 0 0 0 0 0 0 0 0 1 0 0 1 0 0 0 0
	300000111110110100000000010111
	4 0 0 0 0 0 1 0 0 1 0 1 1 0 1 0 0 0 0 0
	50000010010101100000000011011
CASOS	6 0 0 0 0 1 0 0 0 0 1 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 0
Une 13	, 2006 Copyright © 2006 Kathleen M. Carley, CASOS, ISRI, SCS, CMU 36

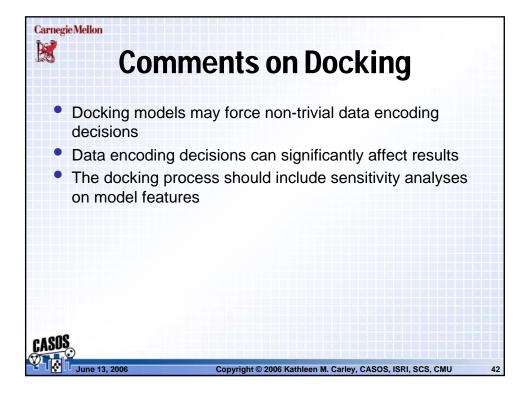


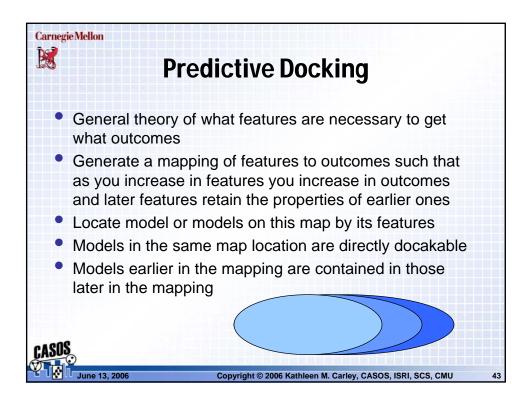




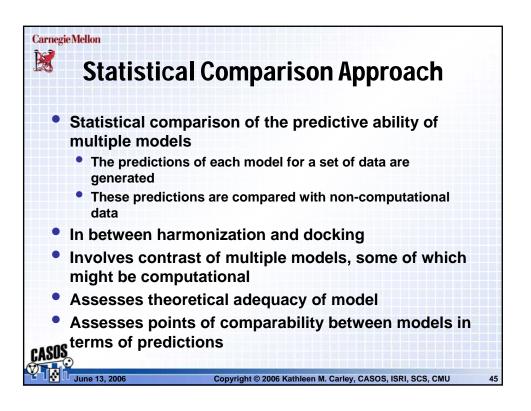


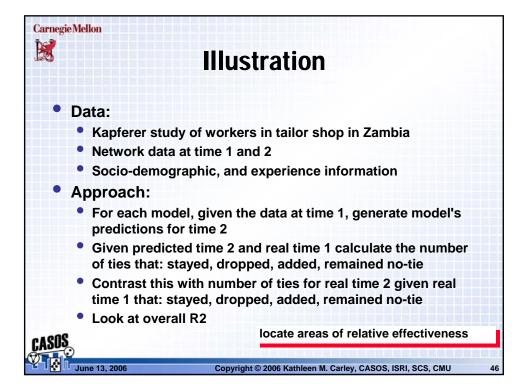
	Models	
Carley, Kj	jaer-Hansen, Prietula & No	ewell 1991
	Plural-Soar	ELM
Perception and Action Perceives the environment Physically manipulates objects Moves self to different locations		•
Memory Location People Task	•	000
Instruction Can be incomplete	0	0
Task Analysis Decomposes task Coordinates subtasks for self to do		
Communication Skills Asks questions/Provides answers	0	0
Gives commands/Receives commands Talks to a single individuals/Talks to a group	p 0	00



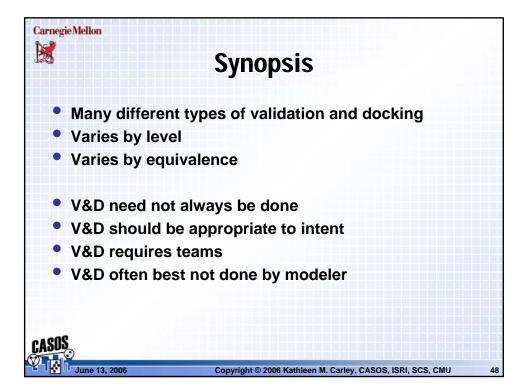


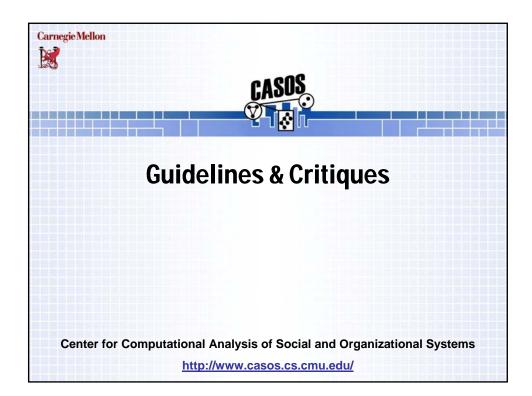
Cognitive Architecture		In	Knowled creasingly Rich	e		>
Increasingly Limited Capabilities	Nonsocial Task	Multiple Agents	Real Interaction	Social Structural	Social Goals	Cultural Historical
Omniscient Agent	goal directed produces goods uses tools uses language	models of others turn taking exchange	face-to-face	class differences	organizational goals	historically situated
Rational Agent	reasons acquires learns	learns from others education negotiation	mis- communication	promotion social mobility	competition cooperation social cognition	emergent norms Cultural Transmission
Boundedly Rational Agent	satisfices task planning adaptation	group making	social planning coercion priority disputes	altruism uses networks for information boundary spanners Garbage Can Model Sugarscape, AAIS	delays gratification moral obligation VDT TAEMS	gate keeping role emergence CORP, HITOP-A, ACTION, ORGAHEAL Organizational Consul
Cognitive Agent	compulsiveness lack of awareness multi-tasking	group think	spontaneous exchange social interactions	automatic response to status cues	group conflict power struggles TAC Air Soar Plural-Soar	develop language institutional change
Emotional Cognitive Agent	habituation variable performance	protesting trust	play rapid emotional responce cons	campaining	team player	norm maintenance ritual maintenace advertising MODEL SOCIAL AGENT
Aure 13, 20	06	Copuri	nht © 2006 Kathl	een M. Carley, C		





	Chang	je ir	Int	eractio	on		
	MODEL	R	never	continue	begin	stop	Total
	Random	.000	572 67%	74 33%	91 33%	85 67%	822 56%
	Kapferer's Exchange	.225	632 74%	168 76%	108 39%	4 3%	912 62%
	Heiderian Balance	.339	224 26%	222 100%	242 88%	0 0%	688 46%
DS	CONSTRUCT	.422	662 77%	215 97%	140 51%	1 1%	1018 69%





rje Mellon	
Guidelines	
KISS	
Keep the key experiment in sight	
No theory is sufficient	
Take a building block approach	
Be willing to start over	
Keep virtual field notes, a lab notebook	
Minimize the number of parameters	
Don't hardwire parameters	
Don't hardwire input data	
if you must use fixed parameters have a low, medium,	
high option	
if you don't run a virtual experiment for this parameter	
then monte-carlo across it (randomly set its value for	
seach run)	
	50
	Guidelines KISS Keep the key experiment in sight No theory is sufficient Take a building block approach Be willing to start over Keep virtual field notes, a lab notebook Minimize the number of parameters Don't hardwire parameters Don't hardwire input data if you must use fixed parameters have a low, medium, high option if you don't run a virtual experiment for this parameter

